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A Review of Machine Learning Applications to Disruptions

Cristina Rea with S. Benjamin¹, P. Kaloyannis^{1,2,4}, Z. Keith¹, A. Maris¹, L. Spangher¹, H. Turner¹, J.X. Zhu¹, C. Clauser¹, R.S. Granetz¹, R.A. Tinguely¹, A. Pau², J. Barr³, M.D. Boyer⁴, R. Sweeney⁴, K. Felker⁵, K.G. Erickson⁶

¹MIT Plasma Science and Fusion Center, Cambridge, MA, USA ²EPFL Swiss Plasma Centre, Lausanne, Switzerland ³General Atomics, San Diego, CA USA ⁴Commonwealth Fusion Systems, Cambridge, MA USA ⁵Argonne National Laboratory, Lemont, IL USA ⁶Princeton Plasma Physics Laboratory, Princeton, NJ USA

Theory and Simulation of Disruptions Workshop Princeton Plasma Physics Laboratory, July 20th, 2023



EPFL

Swiss

Plasma

Center

PSFC

C. Rea | TSDW | 07/20/23

MIT Global Experiences

- 1. Intro and motivations
- 2. Explainable and adaptive Machine Learning for disruption prevention
- 3. Conclusions

Precursor's prediction and detection crucial to avoid disruptions, but challenging task!



No first-principle solution to capture predisruptive chain of events



DENSITY LIMIT



- Statistical studies on disruption frequency (and type) not available across different tokamaks.
- Notable efforts on event analyses on KSTAR, MAST, NSTX/-U dbs → DECAF

Sabbagh et al PoP 30 032506 (2023) and later talk

- Wealth of experimental data from different tokamaks enables Machine Learning applications.
- Need timely identification of precursors to allow the plasma control system (PCS) to take proper avoidance action.

Courtesy: A. Pau, PSFC seminar, April 2023

De Vries et al. NF 51 (2011) 053018 "Survey of disruption causes at JET"

Active monitoring and prediction of soft/hard limits necessary to inform transition across operational boundaries

Adapted from J. Barr IAEA TM PDM 2020 and Sammuli et al 2021 Fusion Eng. Des. 169 112492



Data-driven models developed to provide

- Explainable proximity to unstable operational space
- Interpretable tracking of instability onset

Established multi-machine databases of disruption-relevant parameters foundational to ML applications

- SQL dbs of times series for > 50 plasma signals
- Annotated events
 - o disruptive vs non-disruptive,
 - H-L back transitions,
 - radiative collapses,
 - o density limit,
 - o ...

Rea et al, 2018 Plasma Phys Control. Fusion 60 084004 Montes, Rea et al, 2019 Nucl. Fusion 59 096015

Device	Discharges	Samples
C-Mod	5,500	500,000
DIII-D	13,000	3,000,000
EAST	19,000	1,500,000

- **DisruptionPy**: interoperable library for data retrieval and database development across different devices
 - Modular structure + version controlled
 - Available for Alcator C-Mod and DIII-D, soon EAST





Adapted from A. Pau et al, Nuclear Fusion, 59(10):106017, 2019

1. Intro and motivations

- 2. Explainable and adaptive Machine Learning for disruption prevention
 - DPRF

0

SORI

- Available in real-time at DIII-D
- Hybrid Deep Learning modeling
- Proximity-to-instability
- Time-to-event frameworks
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Explainable ML for disruption prediction and stability boundaries identification in real-time

- Disruption Prediction via Random Forest computes probability of an impending disruption, while interpreting its drivers in real-time.
 - Available on DIII-D and EAST.



Rea et al, 2021 IAEA EX/P1-25,

9

J. Barr et al, Nucl. Fusion 61 (2021) 126019

DPRF

Real-time implementation and optimization for asynchronous avoidance and emergency response



Real-time model evaluation and feature contribution computation: < 200 µs

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Emergency

Avoidance

DMS trigger



Off-Normal Fault Response \rightarrow **Asynchronous and Emergency response**.

Eidietis et al., 2018 Nucl. Fusion 58 056023

Used to regulate plasma stability and performance in **DIII-D Proximity Control architecture**



Safe operating regions identification (SORI) through DPRF for disruption-free trajectory planning



SORI

Time [s]

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 - DPRF
 - o SORI
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more at APS-DPP 2023

Hybrid Deep Learning architecture for cross-machine disruption prediction using time series data



Scenario-adaptive Hybrid Deep Learning predictor as DMS trigger candidate (ITER/SPARC)

- Adapt current state-of-the-art ML predictors to different operational regimes across devices (DIII-D/EAST).
- Adaptive strategies:
 - ad-hoc design of training sets to match target domain by fully exploiting existing data¹,
 - **retrain predictors** after performance degradation².

Adapted from ¹J.X. Zhu, Rea et al, Nucl. Fusion (2021) 114005 ²J. Vega et al., *Nat. Phys.* 18, 741–750 (2022)



Hybrid Deep Learning architecture optimized for precursor identification via multi-task learning



Symbolic ML for disruption-free operations in regimes close to density-limit

Density is critical design parameter:

→ fusion power density $\propto n^2$

 $\frac{n}{n_G} < 1$, where $n_G = \frac{I_p}{\pi a^2}$

Edge

temp. ↓

Power plant design points usually close to the empirical density limit Greenwald et al., Nucl. Fusion (1988)

Temp. instability Better (interpretable) tools needed to understand & avoid density limit events:

- Focus on DIII-D data
- Extension to other devices (C-Mod, EAST, TCV, AUG)



Berkery et al 2023 Plasma Phys. Control. Fusion in press Manz et al 2023 Nucl. Fusion 63 076026; Zanca et al 2019 Nucl. Fusion 59 126011; Giacomin et al 2022 Phys. Rev. Lett. 128 185003; Singh and Diamond 2022 Plasma Phys. Control. Fusion 64 084004; Stroth et al 2022 Nucl. Fusion 62 076008; Brown and Goldston 2021 Nucl. Mater. Energy 27 101002; Bernert et al Plasma Phys. Control. Fusion 57 (2015) 014038; Maraschek et al Plasma Phys. Control. Fusion 60 (2018) 014047; ...

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density limit

Edge density

Symbolic ML to find data-driven risk for n=1 TM onset

- Backward feature elimination and probabilistic model selection combined to identify the "TM risk"
- Features:

Dimensionless: β_p , q_{95} , n_G , Te_width_norm, κ , ν_* , l_i , q_0 , radiated_frac, ip_error_frac Dimensional : I_p (MA), B_{tor} , V_{loop} , n2rms (Gauss)

- Focus on ITER Baseline scenarios
 - boundary version available for scenario-agnostic runs

$$\mathbf{TM \ level} \coloneqq 0.20\beta_p + 0.01\nu_* + 1.81 \frac{\sqrt{q_{95}T_{e_{width,norm}}}}{\kappa} + 1.69|\frac{I_p \times 10^{-6}}{B_{Tor}}| - 3.1$$

Available in real-time at DIII-D





tearing

stability

DIII-D real-time qualification of data-driven TM risk during FY22

- LRHO DIII-D experiment (summer 2022)
- TM level integrated with ONFR (K. Erickson, J. Barr)
- Experimental plan to sweep TM level parameters (Ip, Bt, ...) inter and intra shot and to scan thresholds in TM level and time delay
- Goal: trigger the ONFR for soft landing or TM avoidance.
- Successful IBS TM avoidance example: Level down Ip at 1.35MA (from 1.5MA) and trigger soft landing using ONFR and TM risk.

Available in real-time at DIII-D





Towards tearing onset prediction with physics-informed Machine Learning for scenario design

- Physics-informed ML tearing stability metric for time-independent magnetic equilibria
- Initial study with classical tearing stability, synthetic data:
 - Equilibria in cylindrical geometry generated and evolved linearly in M3D-C1
 - Predictive tool will leverage:
 - observed M3D-C1 growth rates
 - Δ ' in the constant-psi approximation
 - ratios of big and small asymptotic solutions in inner resistive-MHD and outer ideal-MHD regions about the rational surface
 - growth rates from asymptotic matching
- Tearing mode database project (TMDB): a community-driven db to study ML-accelerated tearing stability
 - Collect stability terms (community-driven)
 - Focus on DIII-D data, expand to C-Mod, ...
 - Provides NTM phenomena to ML predictor
- TMDB will be publicly available

Benjamin, Clauser, Rea, Sweeney, ongoing work

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Predict "time-to-disruption" risk using ML-driven classification probability





Any classification probability (P_D) cast between [0,1] can be used to:

- Predict the future probability of plasma survival S(t+\Delta t | t) or
- Model the **instantaneous hazard** \hbar =d lnS/dt to be used as probability generator.

Hazard function modeling connects dynamical systems and risk-aware control design by probability generation.

C-Mod data used as proof of concept to combine DPRF (or <u>any classifier</u>) disruptivity with survival analysis.

Tinguely, Montes, Rea et al 2019 PPCF 61 Olofsson et al 2018 PPCF 60 Olofsson et al 2018 FED 146 Continued work by Keith, Rea, Tinguely (MIT)

Defining data-based disruptivity in statistically robust way

- Disruptions modeled as Poisson processes with stability time inferred from database analysis: • $P(k \text{ disruptions in } \Delta t|d) = \frac{(d\Delta t)^k e^{-d\Delta t}}{k!} \longrightarrow P_D(\Delta t|d) = 1 - e^{-d\Delta t}$ probability of disrupting in next Δt (s)
- Maximum likelihood estimation ensures statistical robustness, even when disruptivity (s⁻¹) very high .



Gradient boundary avoidance from offline disruptivity maps

- From offline disruptivity, create best fit surface over plasma parameters (offline)
- Interpolate surface for the disruptivity (potentially in real-time)
- Compute the disruption probability and map's gradient
- Apply gradient descent, weighted by disruption probability

Kaloyannis (EPFL), Rea, 2023 Master's thesis





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LabelProp

Montes, Rea et al 2021 Nuclear Fusion 61 026022

Student-t surrogates

Rath, Rügamer, Bischl, von Toussaint, Rea, Maris et al, 2022 J. Plasma Phys. 88

Disruption prevention solutions via ML



- Fusion energy systems need robust models featuring
 - o interpretability/explainability
 - well-defined validity and extrapolability boundaries (UQ)
 - risk-awareness, conditioned on consequences/effects
- Active disruption research developing
 - a. Interpretable algorithms
 - b. Explainable predictions
 - c. Transfer/adaptive learning
 - d. Time-to-event frameworks
 - e. Data augmentation and labeling
 - f. ..
- MIT team actively contributing to ITER disruption research and SPARC disruption strategies development.

Thank you! < <u>crea@psfc.mit.edu</u> >

