## Findings from a Benchmark Study of 3D Vertical Displacement with JOREK, M3D-C<sup>1</sup>, and NIMROD

C. R. Sovinec,<sup>1</sup> F. J. Artola,<sup>2,3</sup> S. C. Jardin,<sup>4</sup> M. Hoelzl,<sup>3</sup> I. Krebs,<sup>5</sup> and C. Clauser<sup>4,6</sup>

<sup>1</sup>University of Wisconsin-Madison, <sup>2</sup>ITER Organization, <sup>3</sup>Max-Planck Institute for Plasma Physics, <sup>4</sup>Princeton Plasma Physics Laboratory, <sup>5</sup>Dutch Institute for Fundamental Energy Research, <sup>6</sup>Lehigh University

**Theory and Simulation of Disruptions Workshop** 

Virtual Meeting July 19-23, 2021



Center for Tokamak Transient Simulation

### Theme, Outline, and Acknowledgments

Our benchmark study\* for verifying simulations of asymmetric VDE shows strong qualitative agreement and highlights sensitivities that affect some quantitative measures.

- I. Motivation
- II. Problem setup
- III. Code comparison
- IV. Findings
  - A. General evolution
  - B. Wall forces
  - C. 3D Halo currents
  - D. Current asymmetry
  - E. Initial perturbation
  - F. Resolution checks
- V. Discussion and Conclusions

- Work supported by US DOE grant DE-SC0018001 and contract DE- AC02–09CH11466,
- > By the ITER Monaco Fellowship Program, and
- > By the EUROfusion Consortium.
  - Euratom research and training program 2014-2018 and 2019-2020 under grant agreement No 633053
  - ➢ Agreement No. WP19−20-ERG-DIFFER
  - The views and opinions expressed herein do not necessarily reflect those of the European Commission.

\*F. J. Artola, et al., Physics of Plasmas 28, 052511 (2021).

## **Motivation:** Verification benchmarking enhances confidence when applying large simulations codes.

- JOREK,<sup>†</sup> M3D-C<sup>1,‡</sup> and NIMROD<sup>°</sup> are being applied to understand and predict effects from asymmetric VDE.
- The codes have each been verified for many applications, including symmetric VDE,\* but not specifically for asymmetric VDE.
- Comprehensive analytical solutions are not tractable, so verification relies on establishing benchmark problems and performing comparisons.

<sup>+</sup>M. Hoelzl, et al., Nuclear Fusion 61, 065001 (2021).
<sup>‡</sup>N. M. Ferraro, et al., Physics of Plasmas 23, 056114 (2016).
<sup>°</sup>C. R. Sovinec, et al., J. Computational Physics 195, 355 (2004).
<sup>\*</sup>I. Krebs, et al., Physics of Plasmas 27, 022505 (2020).

# **Problem setup:** Our computations are based on NSTX discharge 139536 at 309 ms.

- Case is representative of modeling an actual discharge.
- Feedback in the experiment was removed to allow vertical instability.
- Resistive wall shape is simplified.
- Fitted equilibrium is only used as an initial condition.

Heavy blue "Wall" line indicates the resistive wall used in the computations. [Figure from Artola, *et al.*, PoP **28**, 052511.]



#### The computations are run in two phases: 2D until LCFS contact, then 3D.

- The toroidally symmetric 2D computations are similar to those in Krebs, PoP **27**, 022505.
  - Transport coefficients are larger, making VDE displacement time closer to NSTX.
  - Linear stability to n > 0 is tested over displacement intervals of ¼.
- 3D computations are started from 2D results when the LCSF contacts the lower surface.
  - Thermal conductivities are increased by 150 to start a thermal quench (TQ).
  - Particle diffusivity is increased by 26.
  - Small asymmetric perturbations are applied.



Computed traces of magnetic axis position, plasma current, thermal energy, and net halo current. [From Artola, *et al.*, PoP **28**, 052511.]

#### Modeling is visco-resistive MHD with anisotropic thermal conduction.

- The anisotropic thermal conduction,  $\kappa_{||} = 10^5 \kappa_{\perp}$ , is with respect to the evolving 3D magnetic field.
- Resistivity depends on local, evolving temperature,  $\eta(T) = \eta_0 (T_0/T)^{3/2}$ .

$$\frac{\partial}{\partial t}n + \nabla \cdot (n\mathbf{V}) = \nabla \cdot (D\nabla n)$$

$$\rho\left(\frac{\partial}{\partial t}\mathbf{V} + \mathbf{V} \cdot \nabla \mathbf{V}\right) = \mathbf{J} \times \mathbf{B} - \nabla p - \nabla \cdot \mathbf{\Pi}$$

$$\frac{3}{2}n\left(\frac{\partial}{\partial t}T + \mathbf{V} \cdot \nabla T\right) = -\frac{p}{2}\nabla \cdot \mathbf{V} + \nabla \cdot \left[\left(\kappa_{||} - \kappa_{\perp}\right)\hat{\mathbf{b}}\hat{\mathbf{b}} + \kappa_{\perp}\mathbf{I}\right] \cdot \nabla T + Q - T\nabla \cdot (D\nabla n)$$

$$\frac{\partial}{\partial t}\mathbf{B} = \nabla \times (\mathbf{V} \times \mathbf{B} - \eta\mathbf{J})$$

Note:

- Loop voltage and Ohmic heating are not applied.
- Runaway electrons and radiation effects are not modeled.
- The JOREK modeling here uses reduced MHD, unlike M3D-C<sup>1</sup> and NIMROD.

### Boundary conditions allow flow and magnetic field to decouple at the resistive wall.

- Dirichlet conditions on *n*, *T*, and **V** are applied at the resistive wall.
  - Fixing  $T_w = 15 \ eV = 0.015 \ T_0$  maintains cold-wall conditions that allow field and flow to decouple.
  - Evolution is insensitive to  $V_w$ .\*
- Resistive wall/vacuum magnetic models differ among the codes.
  - Thin wall (JOREK, NIMROD) vs. thick (M3D-C<sup>1</sup>)
  - Boundary element vs. meshed vacuum

\*Bunkers and Sovinec, PoP 27, 112505 (2020).



M3D-C<sup>1</sup> (left) and NIMROD (right) evolve vacuum-**B** over meshed external regions. [Krebs, *et al.*, PoP **27**, 022505] ITER ASDEX Upgrade



JOREK is coupled to the boundary-element STARWALL code that can represent complex 2D shapes. [Strumberger, *et al.*, PoP. **15**, 056110]

### **Code comparison:** Models and numerical methods differ among the three codes.

	NIMROD	M3D-C1	JOREK
MHD model	full	full	reduced used here
Variables	п, Т, <b>V</b> , В	<i>n, T,</i> scalar potentials for V and <b>A</b>	<i>n, p</i> , scalar potentials for V and <b>A</b>
Poloidal representation	39k bicubic or biquadratic elements	reduced quintics, 17.5k nodes	22k Bézier cubics
Toroidal representation	Fourier, $N_{max} = 10, 21$	16 Hermite cubics	Fourier, $N_{max} = 10, 20$
Temporal advance	implicit leapfrog	split implicit	implicit
Resistive wall / vacuum field	thin wall, direct representation	thick wall, direct representation	thin wall, Green's function

• The unique aspects of each makes this benchmarking a substantial numerical test.

### **Findings:** The three codes reproduce strong asymmetric destabilization from wall contact.



A slowly growing (m=2,n=1) is dominant until  $q_{95}$  passes 2, when other components become large. [Figures from Artola, *et al.*, PoP **28**, 052511.]

Poincaré plots (pressure contours) show similar effects on magnetic topology (thermal energy loss).

#### Halo asymmetry evolves with the MHD activity during the rapid quench.



• Energy in *n* = 3 magnetic fluctuation exceeds that in *n* = 1 briefly during the multihelicity saturation. [JOREK plots from Artola, *et al.*, PoP **28**, 052511.]

#### There are nontrivial quantitative discrepancies among some results.

	NIMROD	M3D-C1	JOREK
$max(W_{n=1})$	0.24 kJ	0.37 kJ	0.20 kJ
max( F <sub>horiz</sub> )	1.3 kN	2.7 kN	3.5 kN
Final TQ duration	0.18 ms	0.24 ms	0.14 ms

- Largest discrepancy (factor of 2.7) is in the net horizontal wall force.
- Peak n=1 magnetic energy in M3D-C<sup>1</sup> is largest.
- Other quantitative predictions are in better agreement.



Magnetic fluctuation energy (*n*=1), net vertical and horizontal wall force, and force orientation. [Artola, *et al.*, PoP **28**, 052511.]

#### Peaking of toroidal current depends on numerical wall coupling.



Toroidal current recorded over 10 equally spaced poloidal planes. [Artola, *et al.*, PoP **28**, 052511.]

- NIMROD and M3D-C<sup>1</sup> produce similar levels (2%) of toroidal current asymmetry.
- JOREK analysis shows no asymmetry.
  - The STARWALL coupling does not allow halo current to flow to the wall.
  - Surface currents effectively flow without leaving the JOREK mesh.



Schematic of JOREK halo-current continuity.

# The asymmetric perturbations at the start of the 3D phase affect the long-term evolution.

- Perturbations excite unstable asymmetric modes.
- Amplitude and spatial distribution are usually arbitrary, and they differ among the codes.
- Differing magnitudes were tested in NIMROD and JOREK.
  - All perturbations are initially in a linear phase.
  - Net growth during vertical displacement matters in this configuration.
  - Increase in  $F_{horiz}$  with larger perturbation is 80%.



NIMROD results from computations with perturbations of smaller and larger amplitude. [Artola, *et al.*, PoP **28**, 052511.]

## Different perturbation amplitudes lead to qualitatively different evolution.

- All 3D-phase computations first show weakly growing (2,1).
- With smaller perturbations, q<sub>95</sub> dropping below 2 leads to multi-helicity saturation and TQ.
- With larger perturbations, (2,1) and its harmonics saturate before other helicities are excited.
- Finding is verified with NIMROD and JOREK.



*t* = 1.05 ms *t* = 1.01 ms

Pressure contours from NIMROD and JOREK results with perturbations of smaller and larger amplitude. [Artola, *et al.*, PoP **28**, 052511.]

### Numerical resolution tests have been performed.

- Doubling the number of toroidal harmonics in JOREK and NIMROD computations only makes small quantitative effects.
  - NIMROD computations in this comparison used 2D resistivity.
- A check of poloidal resolution was most easily accomplished by switching NIMROD's elements to biquadratic.
  - Peak *n* =1 magnetic energy is 37% larger.
  - max( F<sub>horiz</sub> ) is only 2.2% larger.



Key results from JOREK and NIMROD with varied toroidal resolution. [Artola, *et al.*, PoP **28**, 052511.]

### **Discussion and Conclusions**

- There is strong qualitative agreement in the evolution predicted by JOREK, M3D-C<sup>1</sup>, and NIMROD.
  - Evolution from vertical motion and wall contact directly influences 3D stability.
  - With sufficiently small 3D perturbations, all three codes show a slowly growing (2,1) followed by multi-helicity saturation.
  - The Ansatz-based reduced MHD in JOREK works well in this application.
- Non-trivial quantitative discrepancies are found.
  - Net horizontal force predictions vary by 2.7.
  - Resolution checks have not accounted for the discrepancies.
- The evolving stability of the profile and non-repetitive behavior makes the results sensitive to initial perturbations.
  - This is unlike many other applications of nonlinear computation in MFE.